

CS-184: Computer Graphics

Lecture #11: Texture and Other Maps

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Today

- Texture Mapping
 - 2D
 - 3D
 - Procedural
- Bump and Displacement Maps
- Environment Maps
- Shadow Maps

Surface Detail

- Representing all detail in an image with polygons would be cumbersome



Specific details

Structured noise

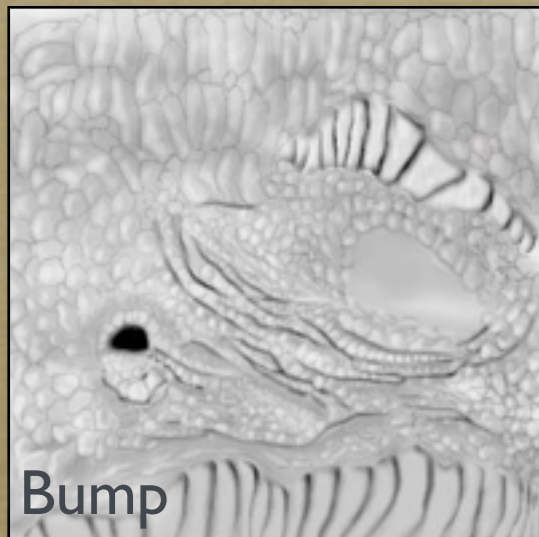
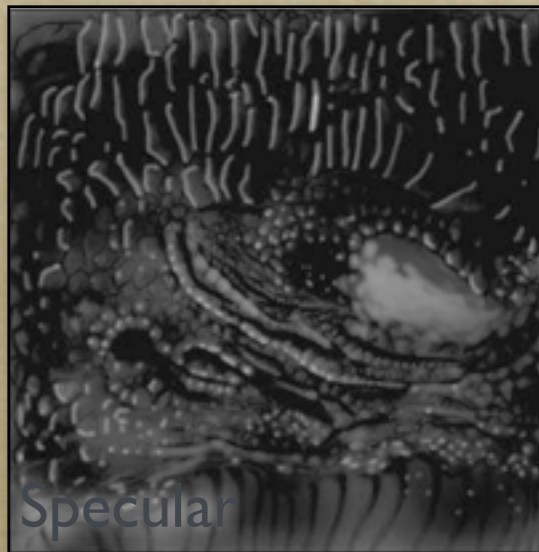
Pattern w/ randomness

Section through volume

Bumps

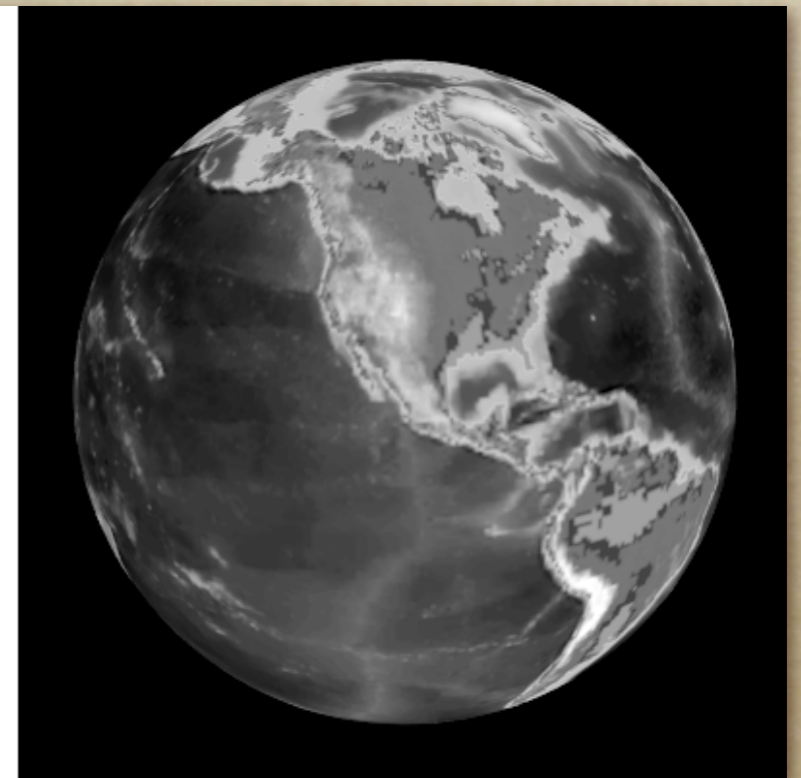
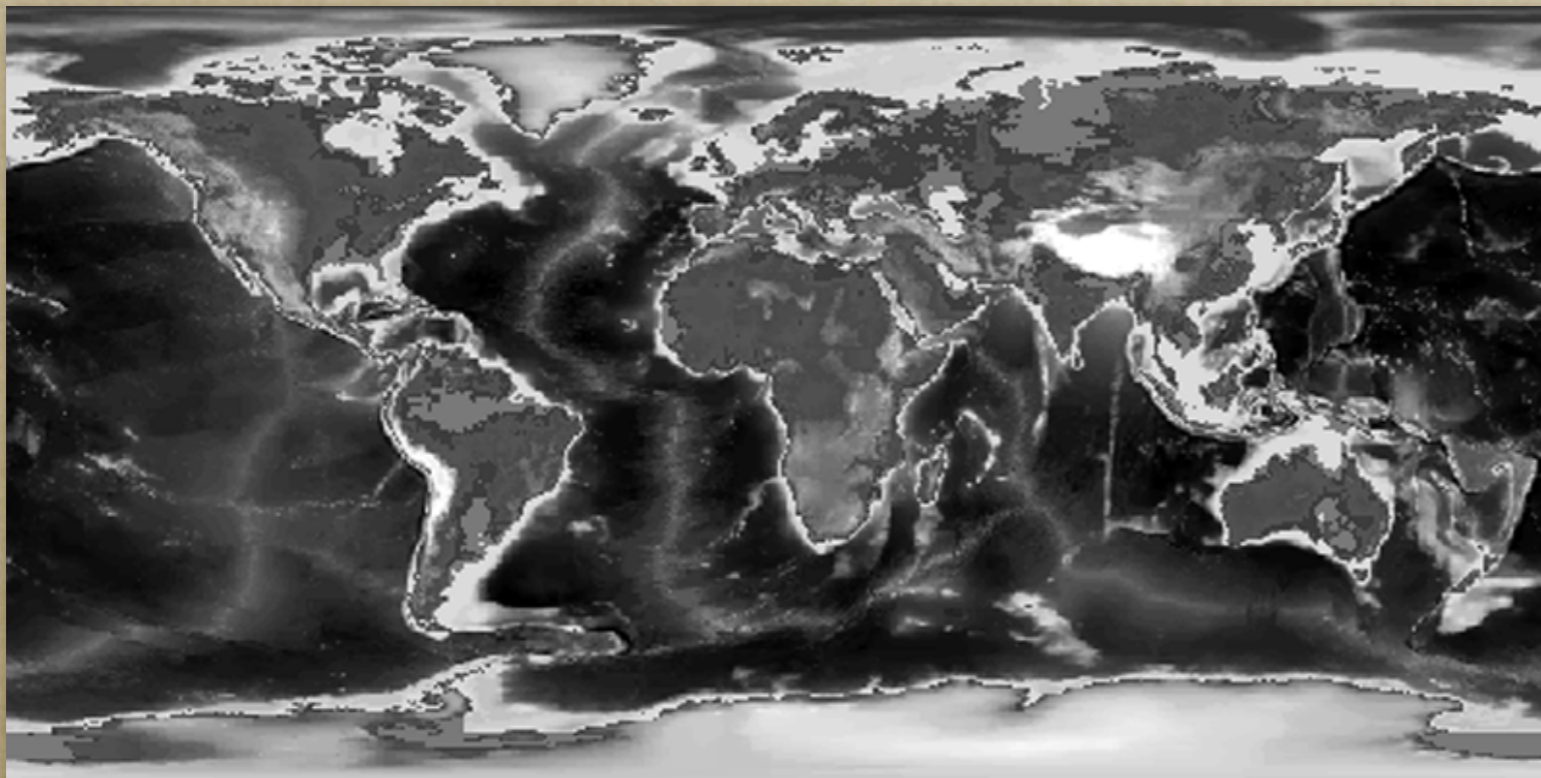
2D Texture Mapping of Images

- Use a 2D image and map it to the surface of an object



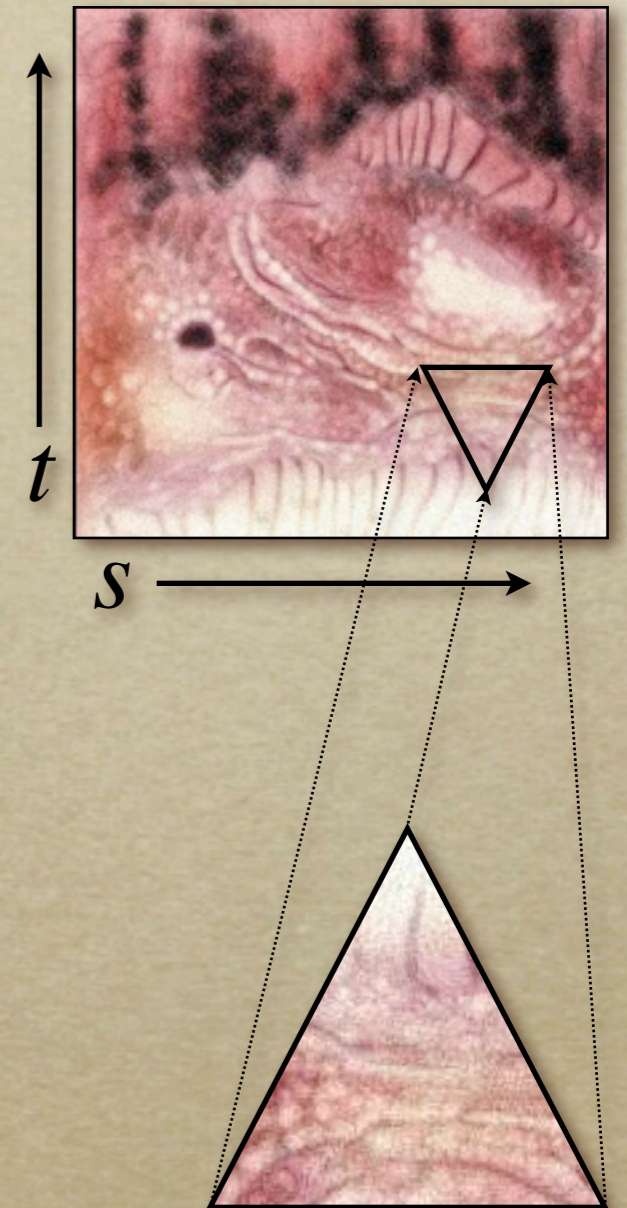
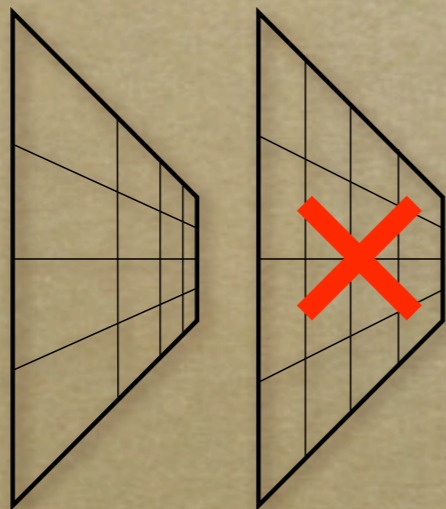
2D Texture Mapping of Images

- Example of texture distortion



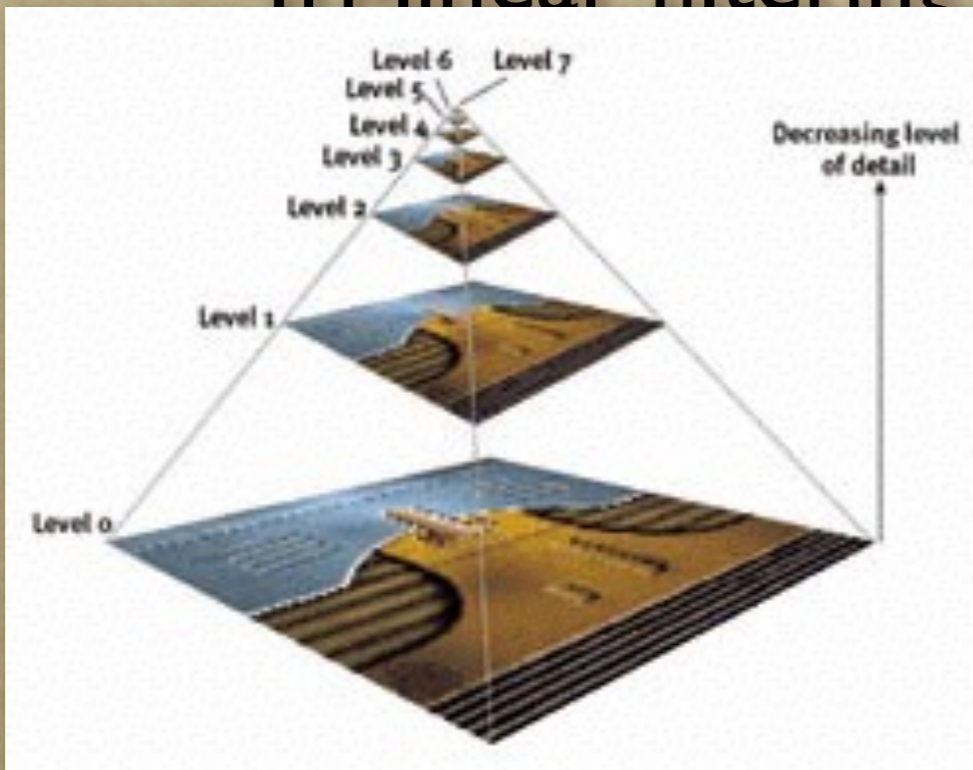
Texture Coordinates

- Assign coordinates to each vertex
- Within each triangle use linear interpolation
- Correct for distortion!



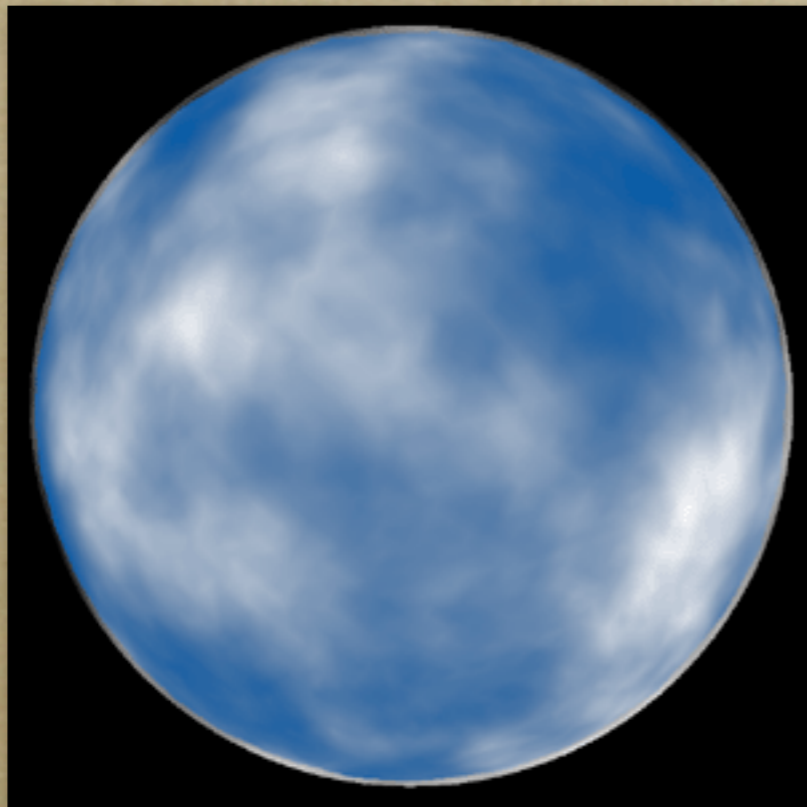
MIP Map

- Pre-compute filtered versions of the texture
 - A given UV rate is some level of the texture
 - Tri-linear filtering $UV \times \text{map level}$



Procedural Textures

- Generate texture based on some function
 - Well suited for “random” textures
 - Often modulate some noise function

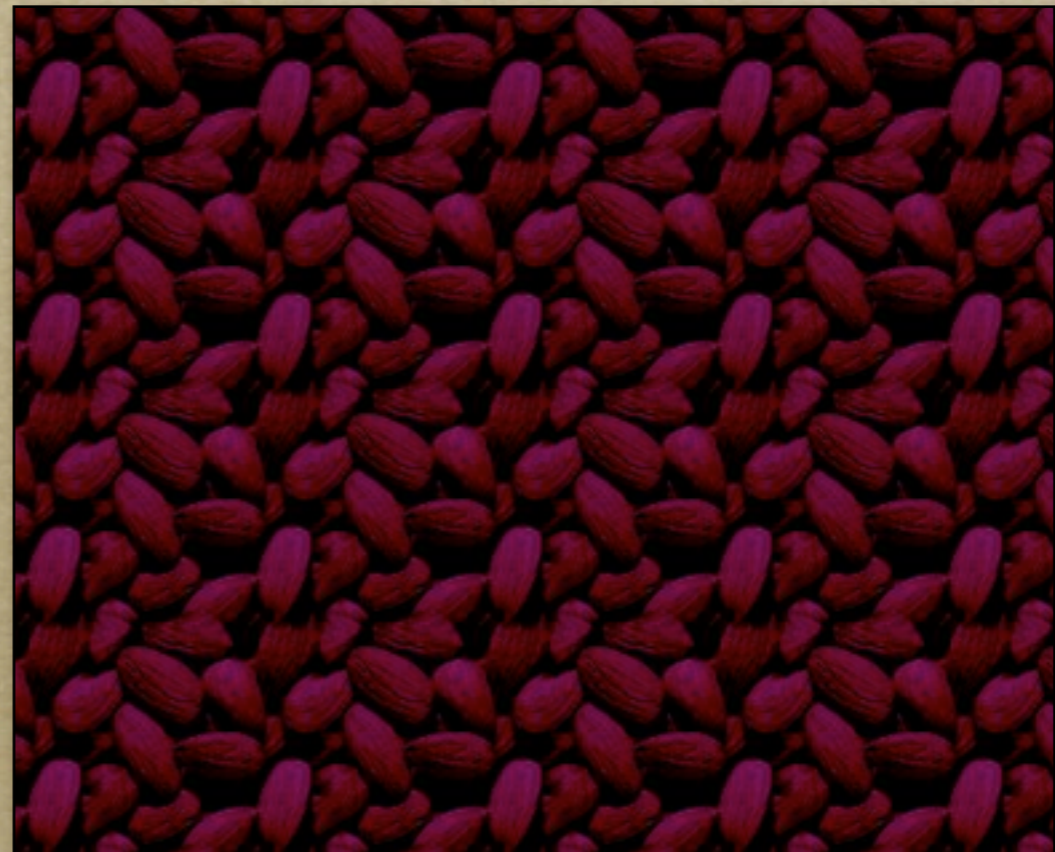
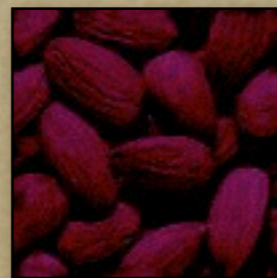


Assigning Texture Coordinates

- Map a simple shape onto object by projection
 - Sphere, cylinder, plane, cube
- Assign by hand
- Use some optimization procedure

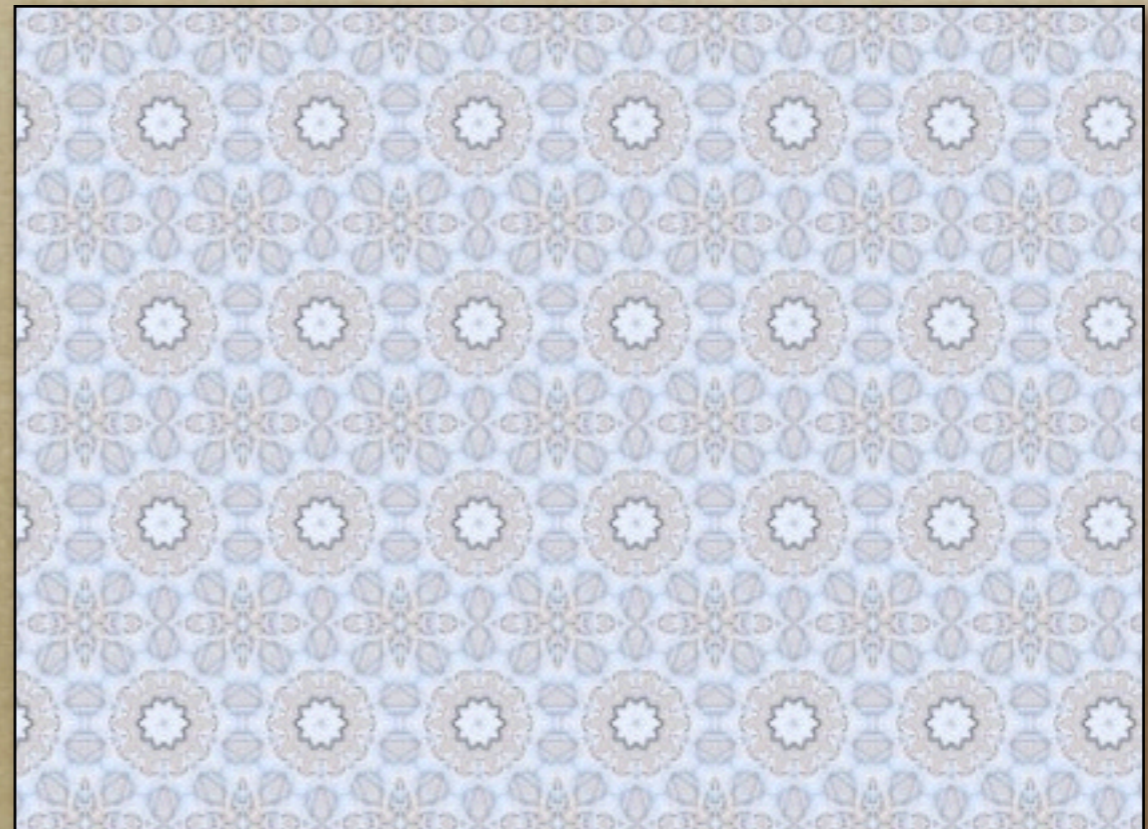
Repeating Textures

- Image Tiles allow repeating textures
 - Images must be manipulated to allow tiling
 - Often result in visible artifacts
 - There are methods to get around artifacts....

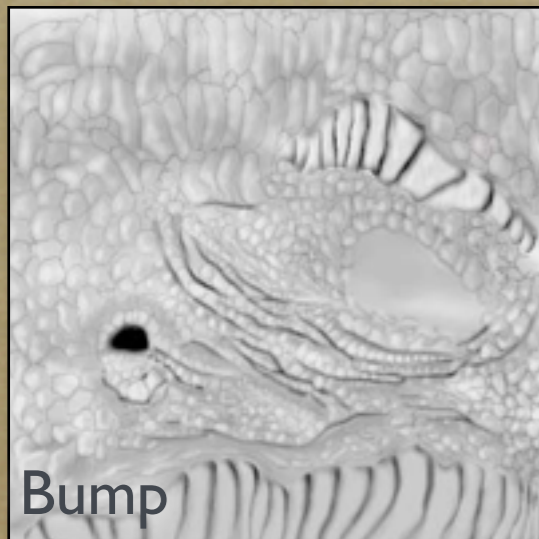
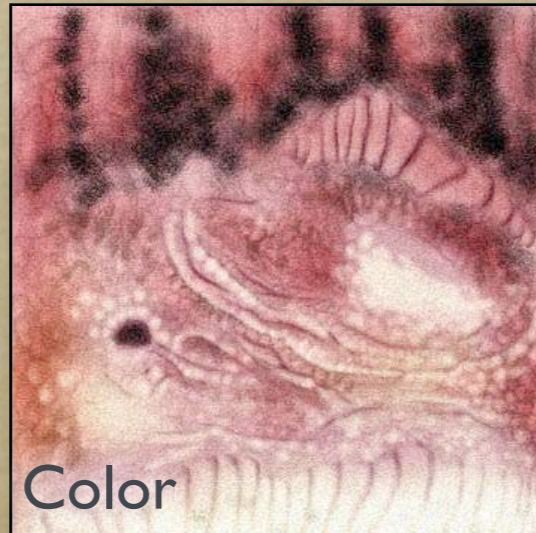
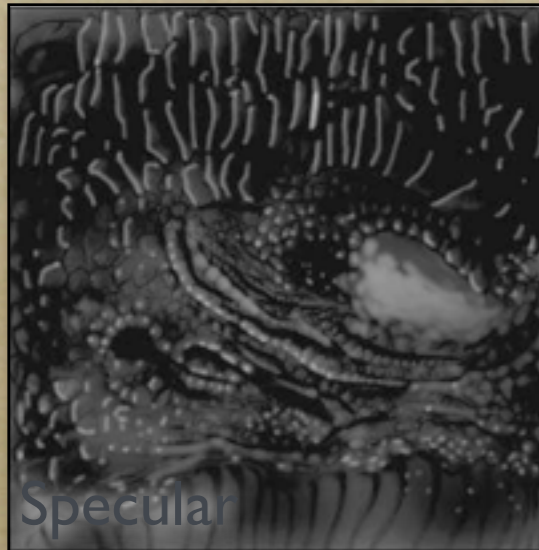


Repeating Textures

- Image Tiles allow repeating textures
 - Images must be manipulated to allow tiling
 - Often result in visible artifacts
 - Artifacts not an issue for artificial textures



Non-Color Textures



Bump Mapping



No bump mapping

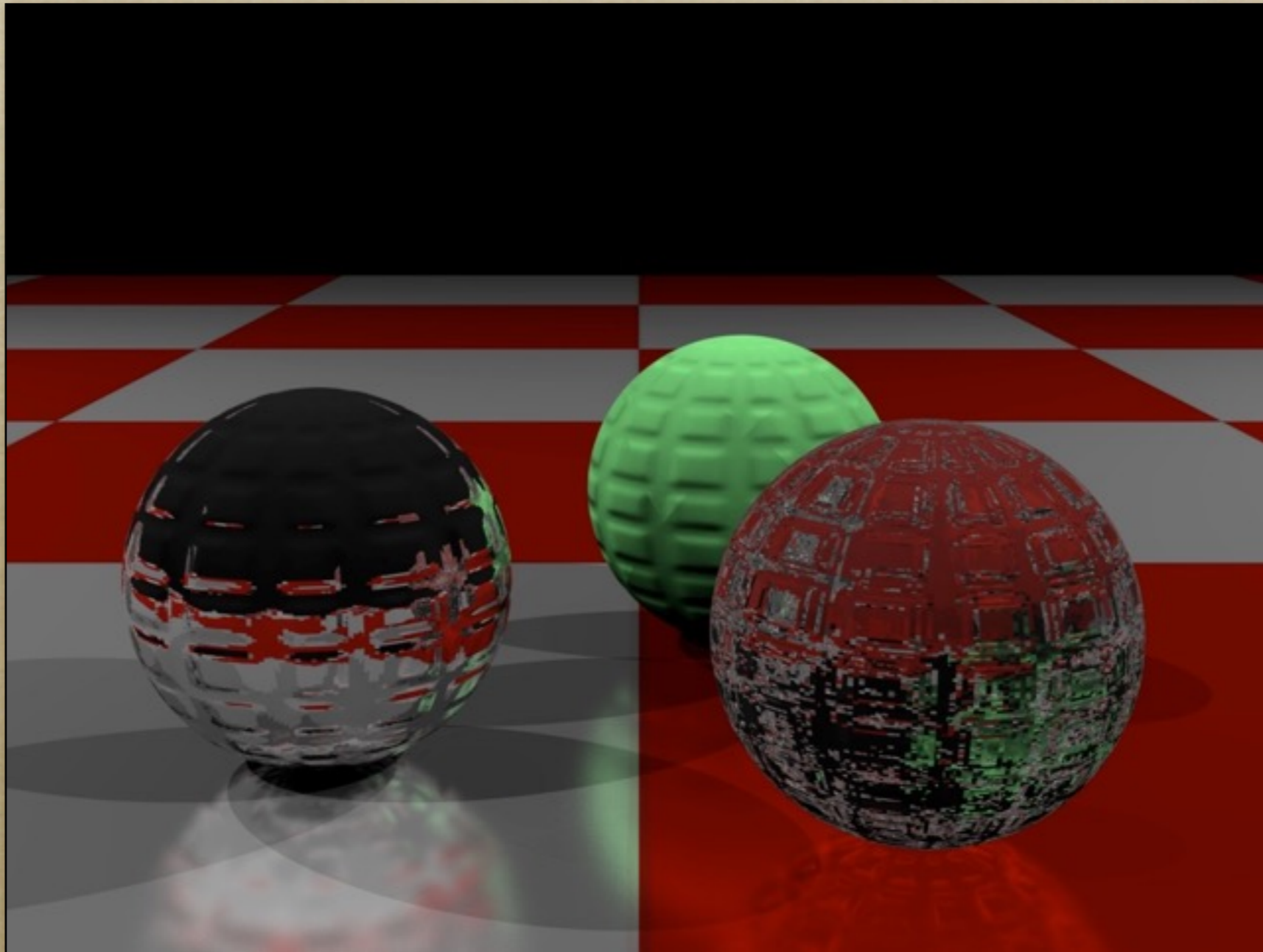


With bump mapping

Bump Mapping

- Add offset to normal
 - Offset is in texture coordinates S,T,N
 - Store normal offsets in RGB image components
 - Should use correctly orthonormal coordinate system
- Normal offsets from gradient of a grayscale image
 - $\mathbf{b}(u, v) = [s, t, n](u, v) = \nabla i(u, v)$
 - $\nabla = \left[\frac{\partial}{\partial u}, \frac{\partial}{\partial v} \right]^T$

Bump Map Example



Catherine Bendebury and Jonathan Michaels
CS 184 Spring 2005

Displacement Maps

- Actually move geometry based on texture map
 - Expensive and difficult to implement in many rendering systems
 - Note silhouette



Bump



Displacement

Environment Maps

- Environment maps allow crude reflections
- Treat object as infinitesimal
 - Reflection only based on surface normal
- Errors hard to notice for non-flat objects

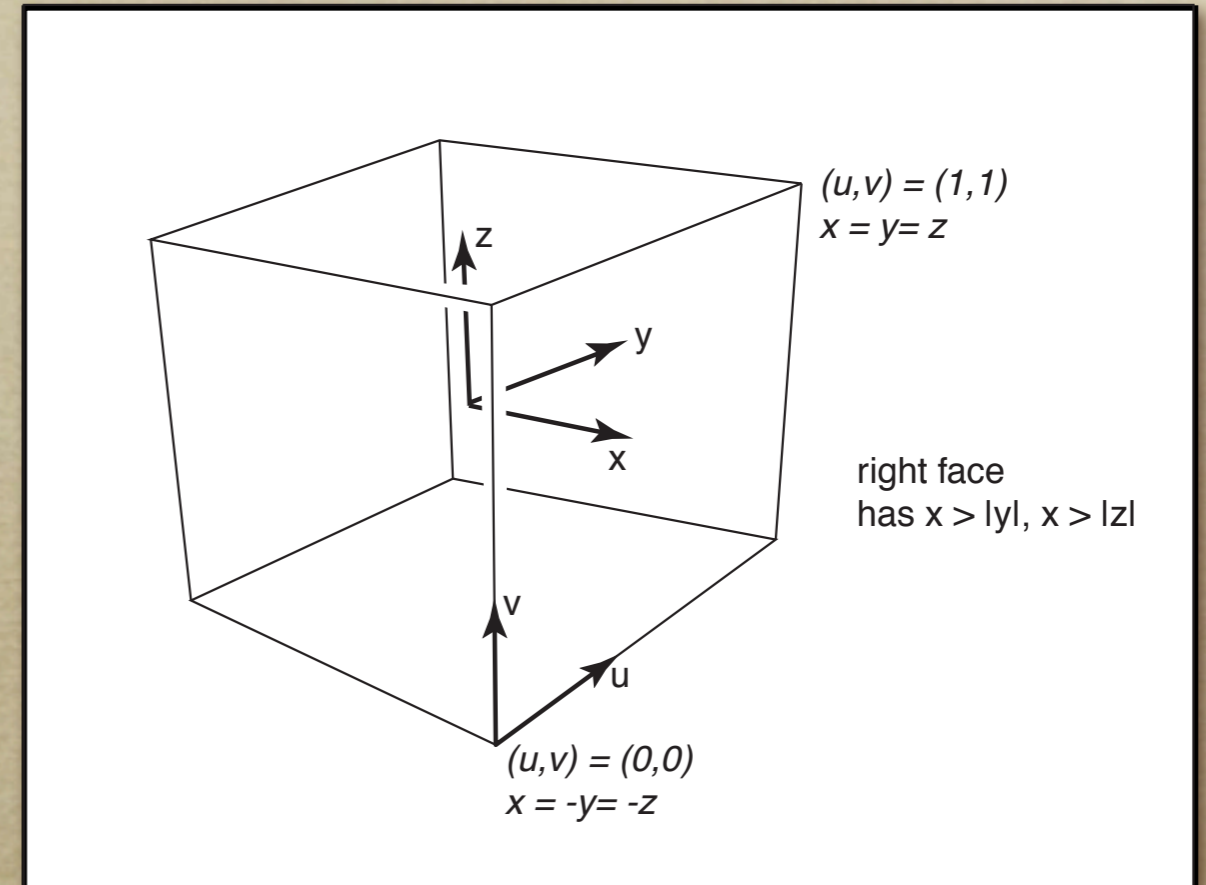
Environment Maps



Environment Maps

$$u = \frac{y + x}{2x}$$

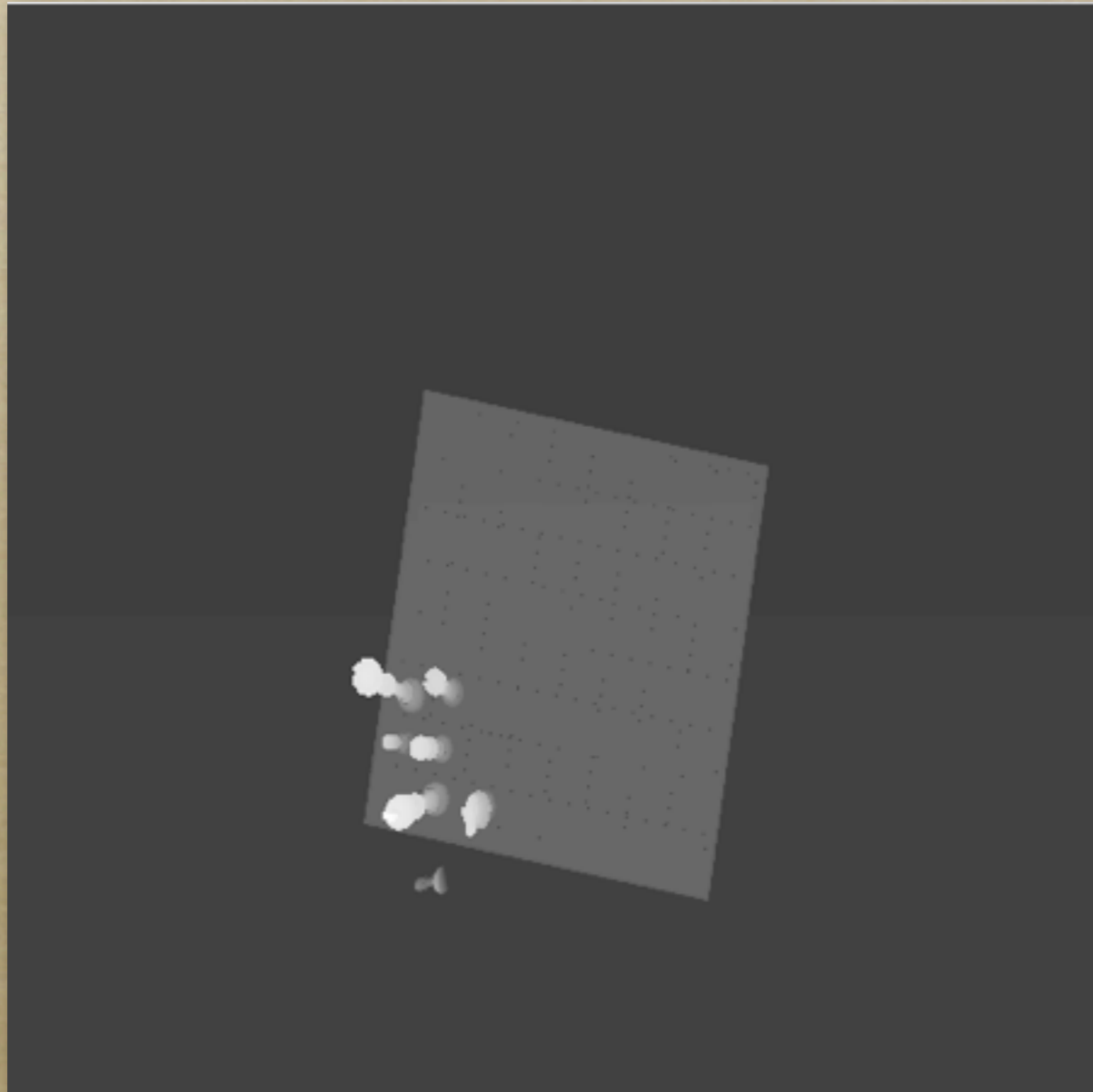
$$v = \frac{z + x}{2x}$$



Shadow Maps

- Pre-render scene from perspective of light source
 - Only render Z-Buffer (the shadow buffer)
- Render scene from camera perspective
 - Compare with shadow buffer
 - If nearer light, if further shadow

Shadow Maps



Shadow Buffer



Image w/ Shadows

From Stamminger and Drettakis
SIGGRAPH 2002

Note: These images don't really go together, see the paper...

Deep Shadow Maps

- Some objects only partially occlude light
 - A single shadow value will not work
 - Similar to transparency in Z-Buffer



From
Lokovic and Veach
SIGGRAPH 2000