CS-184: Computer Graphics

Lecture #19: Motion Capture

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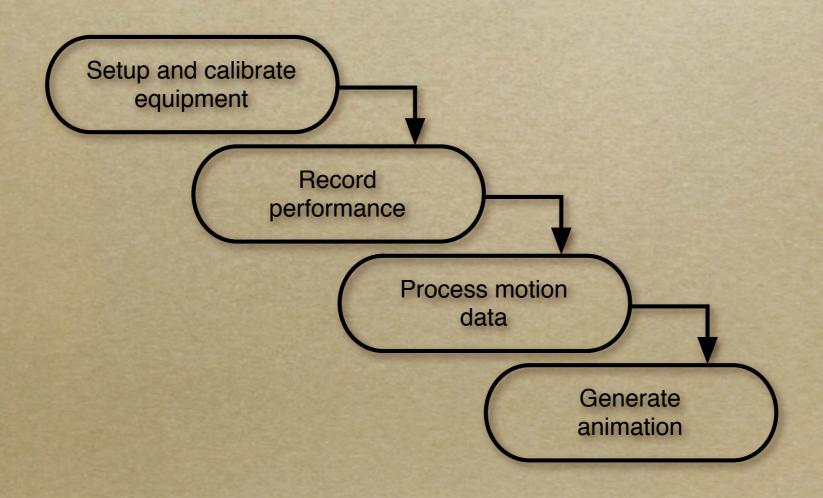
Today

Motion Capture

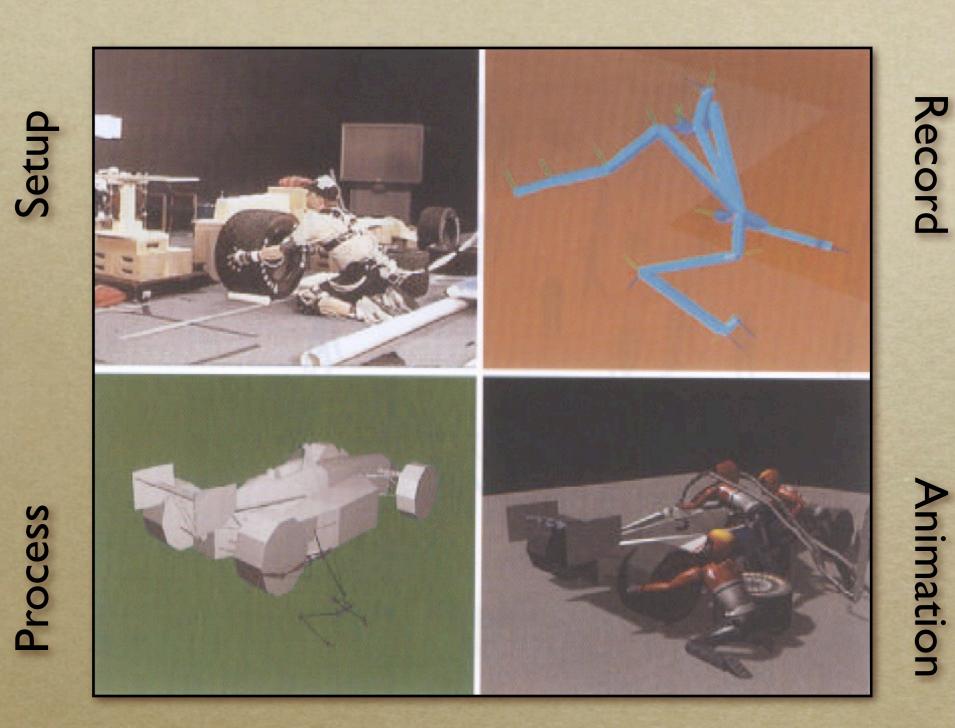
Motion Capture

- Record motion from physical objects
- Use motion to animate virtual objects

Simplified Pipeline:



Basic Pipeline



From Rose, et al., 1998

What types of objects?

- Human, whole body
- Portions of body
- Facial animation
- Animals
- Puppets
- Other objects

Passive Optical

- Reflective markers
- IR (typically) illumination
- Special cameras
 - Fast, high res., filters
- Triangulate for positions



Images from Motion Analysis

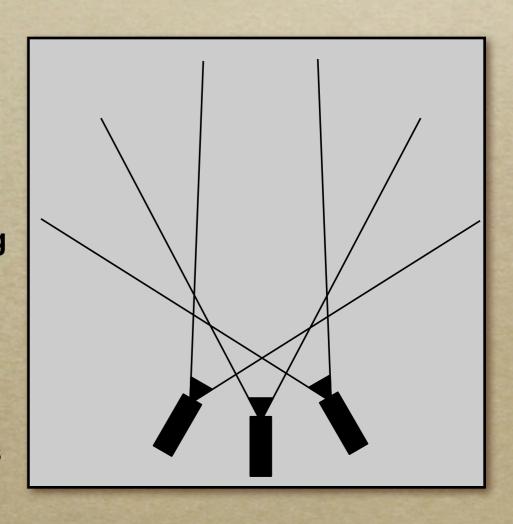




Cappitul Equipment

Passive Optical Advantages Passive Optical Advantages

- Accurate May use many markers
- May use many markers High frequency
- No cables
- High frequency
 Requires lots of processing
- o Disadvantagesive (>\$100K)
 - o Requires 19 rocessing
 - Expensive Marker Swap Systems Lighting/camera limitations
 - Occlusions
 - Marker swap
 - Lighting / camera limitations



Active Optical

- Similar to passive but uses LEDs
- Blink IDs, no marker swap
- Number of markers trades off w/ frame rate

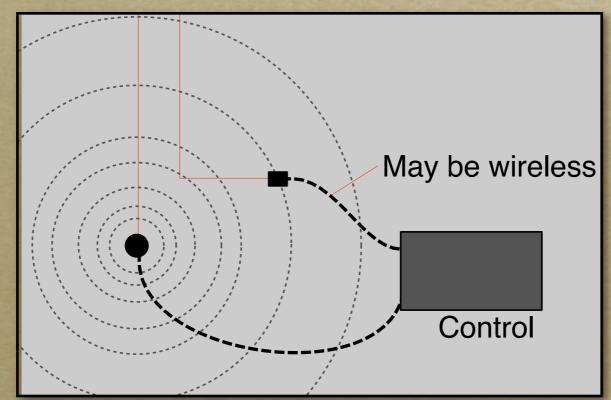


Phoenix Technology



Magnæiæptuælægsipment

- Transmitter emits field
- Magnetic Trackers
 Trackers sense field
 Transmitter emits field
- o Trackerstægersesition and orientation kers report location and orientation

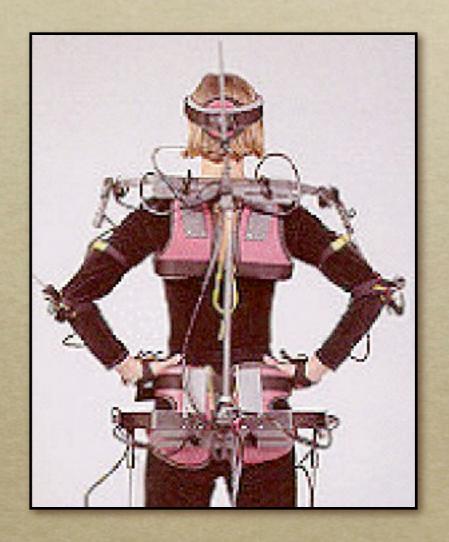




- Electromagnetic Advantages
 - o 6 DOF data
 - No occlusions
 - Less post processing
 - Cheaper than optical
- Disadvantages
 - Cables
 - Problems with metal objects
 - Low(er) frequency
 - Limited range
 - Limited number of trackers

Electromechanical





Analogus

Puppets



Performance Capture

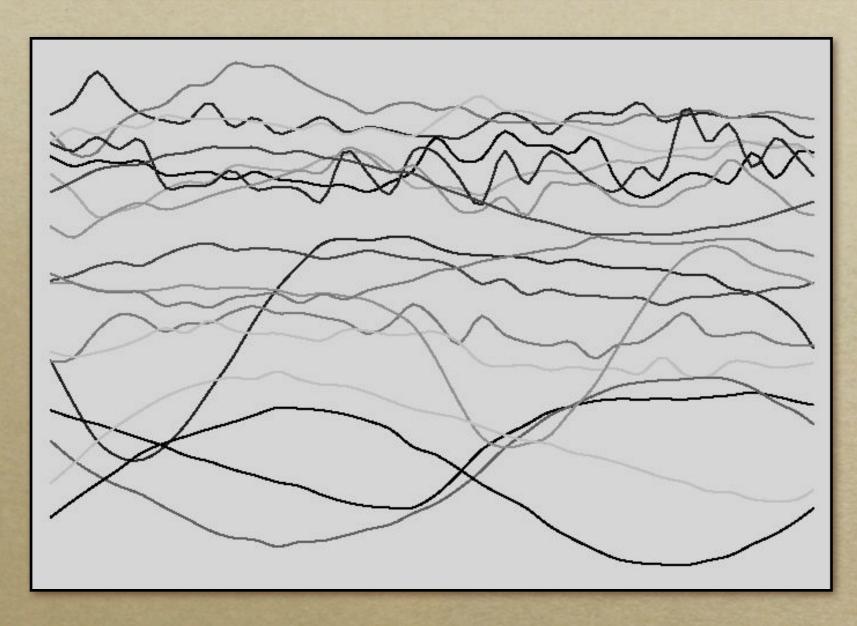
- o Many studios regard Motion Capture as evil
 - Synonymous with low quality motion
 - No directive / creative control
 - Cheap
- o Performance Capture is different
 - Use mocap device as an expressive input device
 - Similar to digital music and MIDI keyboards

Manipulating Motion Data

- Basic tasks
 - Adjusting
 - Blending
 - Transitioning
 - Retargeting
- Building graphs

justing

thy is this task thot trivial? Motion Data



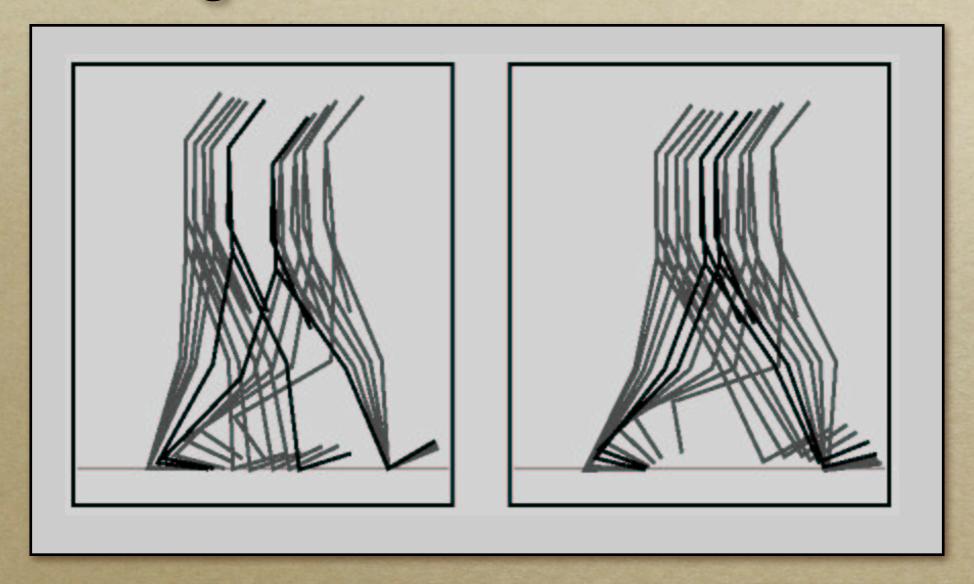
Witkin and Popovic, 1995

Subset of motion curves from captured walking motion.

From Witkin and Popovic, SIGGRAPH 95

Adjusting

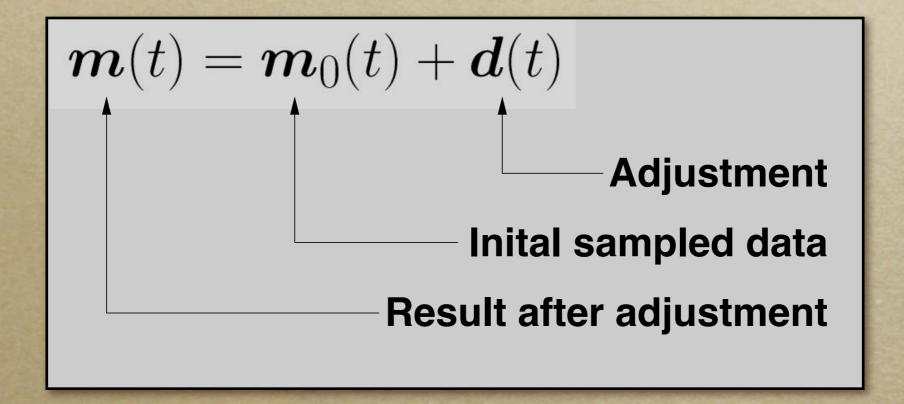
IK on single frames will not work IK on single frames will not work



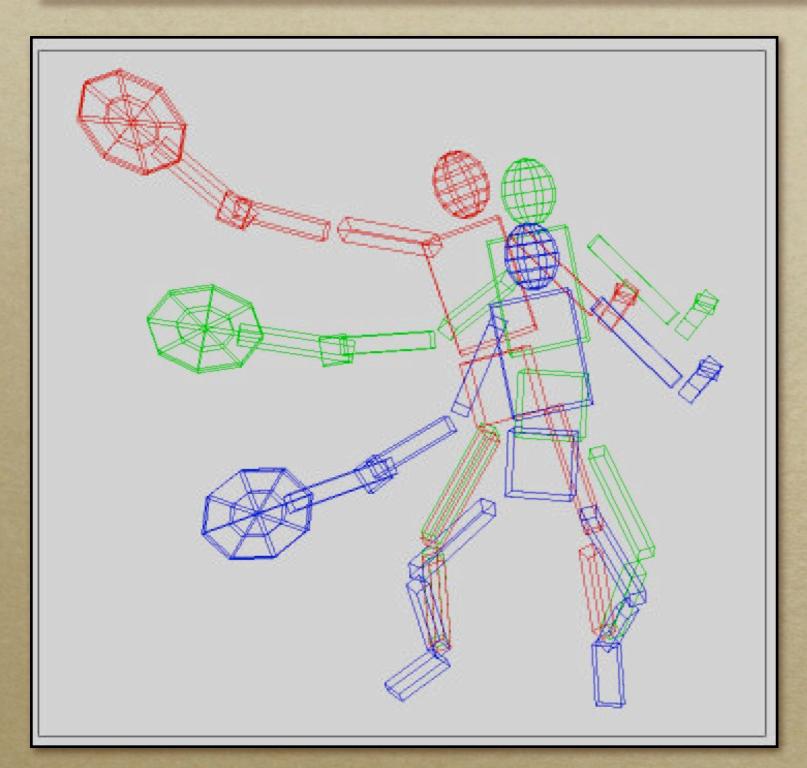
From eighte SIGGRAPH 38

Adjusting Define desired motion function in parts

Define desired function with



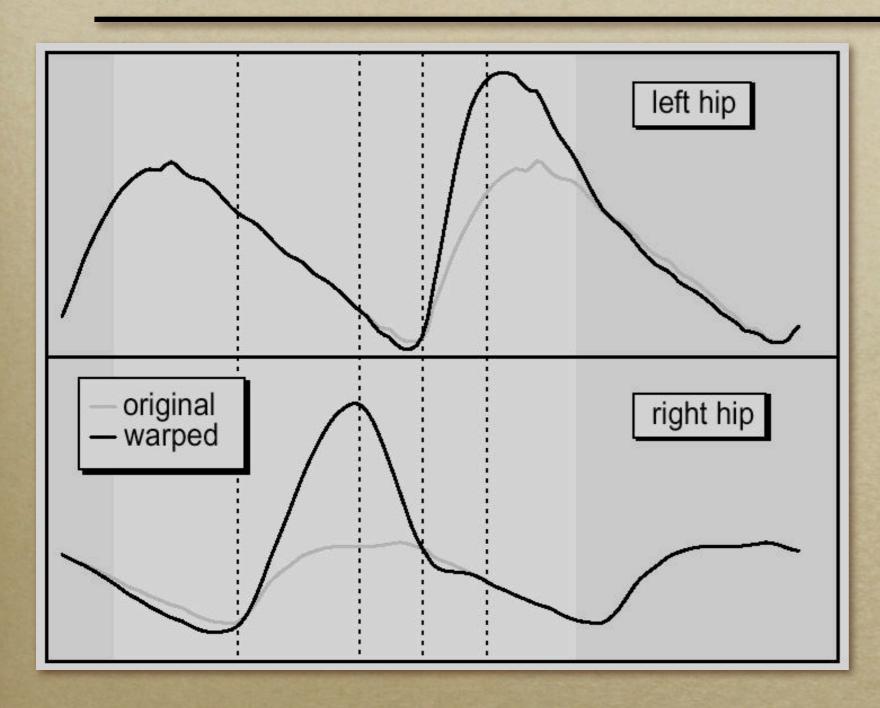
- Select adjustment function from "some nice space"
 - Example C2 B-splines
- Spread modification over reasonable period of time
 - User selects support radius



IK uses control points of the B-spline now

Example:

position racket
fix right foot
fix left toes
balance



Witkin and Popovic SIGGRAPH 95

What if adjustment periods overlap?

Blending

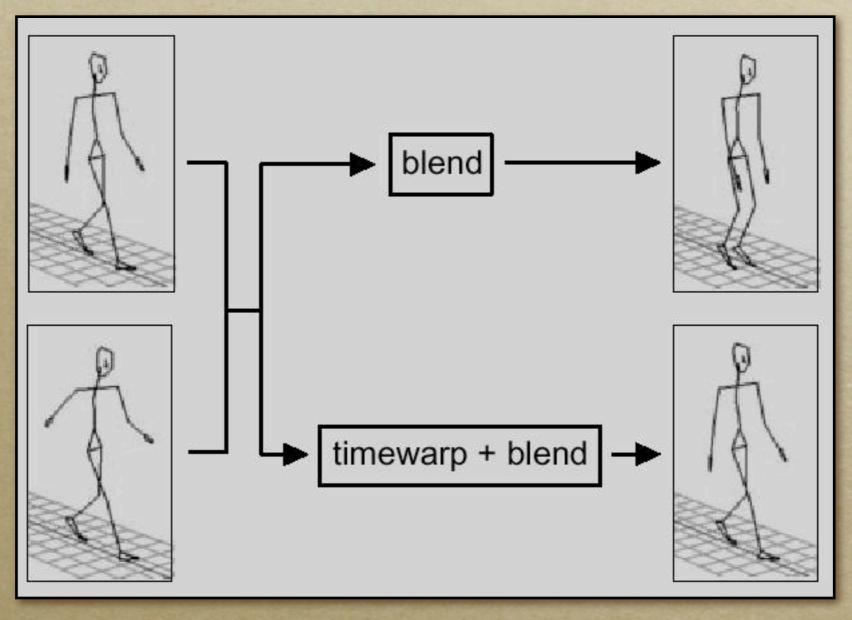
o Given two motions, make a motion that combinies anathered by by them?

$$\boldsymbol{m}_{\alpha}(t) = \alpha \boldsymbol{m}_{a}(t) + (1 - \alpha)\boldsymbol{m}_{b}(t)$$

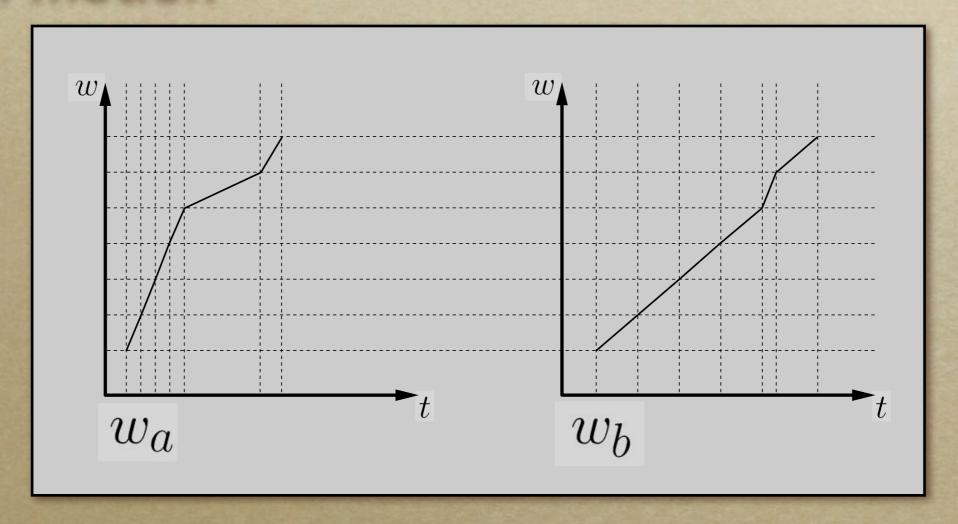
Assume same DOFs

- Assume same DOFs Assume same parameter mappings
- Assume same parameter mappings

Consider blending slow-walk and fast-walk



 Blending
 Define timewarp functions to align features in motions timewarp functions



Normalized time is w

Blending

o Blendindiorpmalizedime

Blend in normalized time

$$\boldsymbol{m}_{\alpha}(w) = \alpha \boldsymbol{m}_{a}(w_{a}) + (1-\alpha)\boldsymbol{m}_{b}(w_{b})$$

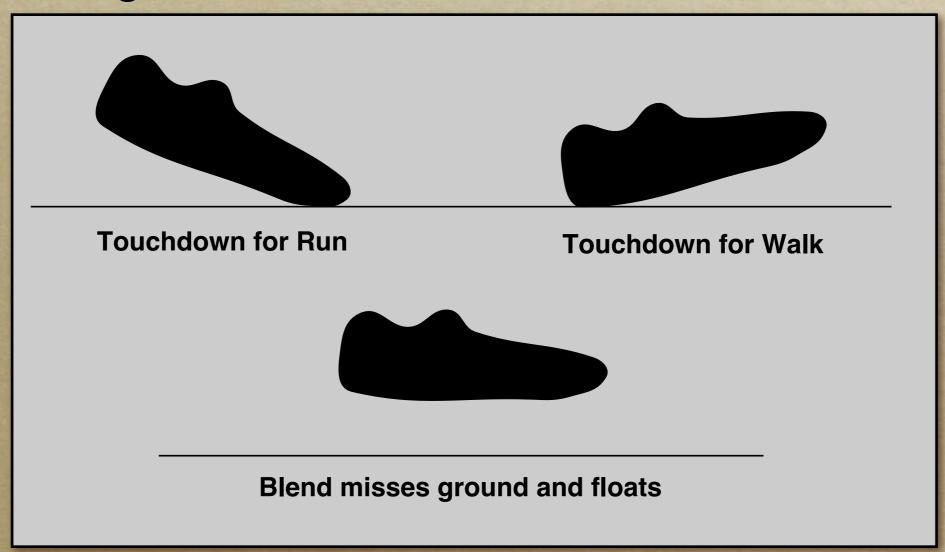
Blend playback rate

Blend playback rate

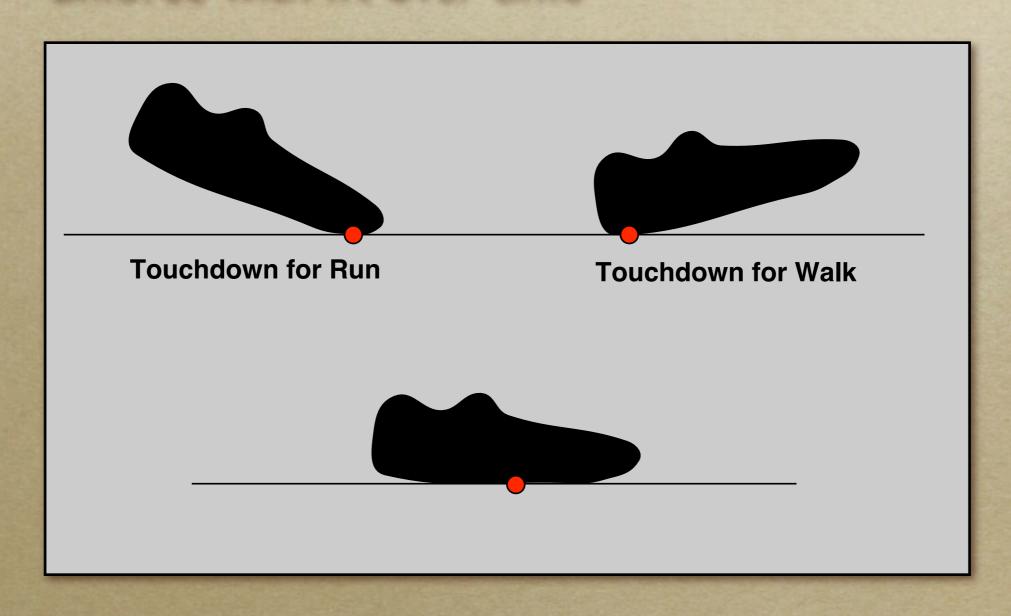
$$\frac{\mathrm{d}t}{\mathrm{d}w} = \alpha \frac{\mathrm{d}t}{\mathrm{d}w_a} + (1 - \alpha)\alpha \frac{\mathrm{d}t}{\mathrm{d}w_b}$$

Blending Blending Blending Break features in original

motions may still break "features" in original motions



- Add explicit constrains to key points
 - o Enforce explicit Robstraints to key points



Blending / Adjustment

- Short edits will tend to look acceptable
- Longer ones will often exhibit problems
- o Optimize to improve blends / adjustments
 - Add quality metric on adjustment
 - Minimize accelerations / torques
 - Explicit smoothness constraints
 - o Other criteria...

Multivariate Blending

Blending

 Extend blending to multivariate interpolation Extend to multivariate interpolation

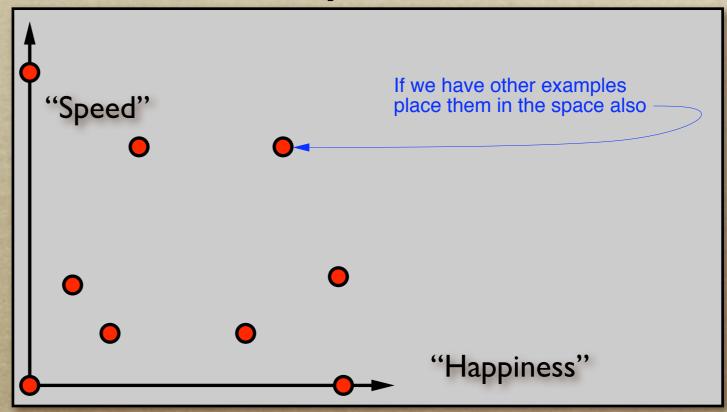
"Speed"
$$m{m}(w) = \sum\limits_{i} \alpha_i(w) \, m{m}_i(w)$$

$$\sum\limits_{i} \alpha_i(w) = 1$$
"Happiness"

Weights are now barycentric coordiantes

Multivariate Blending Blending

 Extend blending to multivariate interpolation Extend to multivariate interpolation

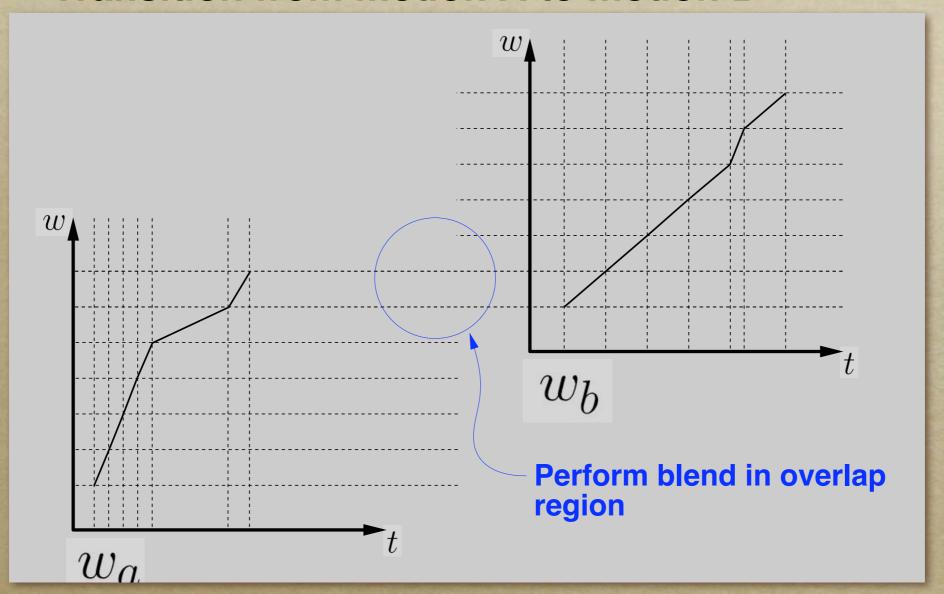


Becomes standard interpolation problem...
Use standard scattered-data
interpolation methods

Transitions

Transitioning

o Transition from one motion to another

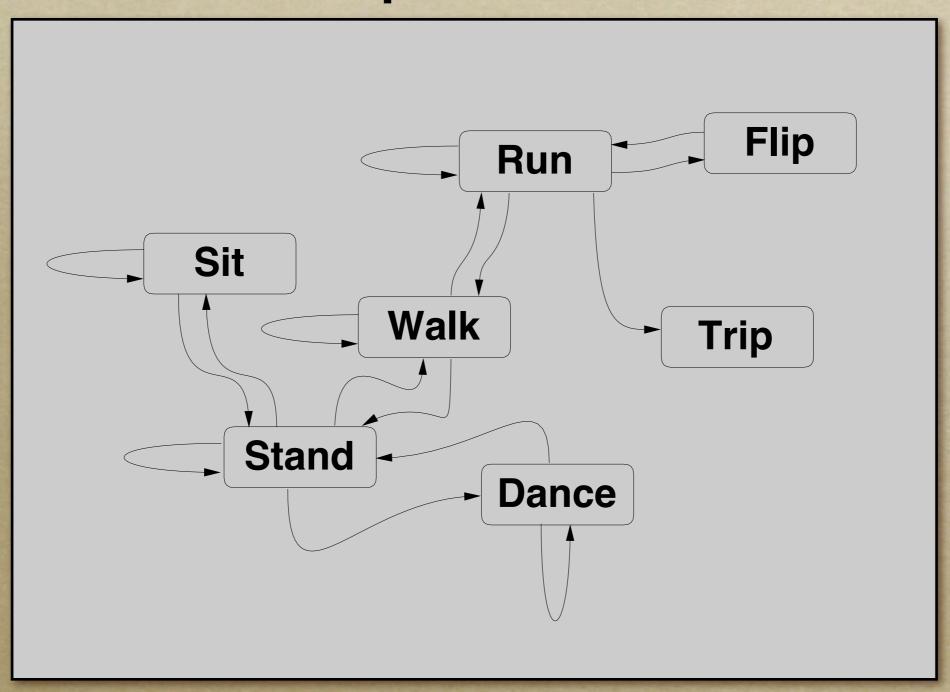


Cyclification

- Special case of transitioning
- Both motions are the same
- Need to modify beginning and end of a motion simultaneously

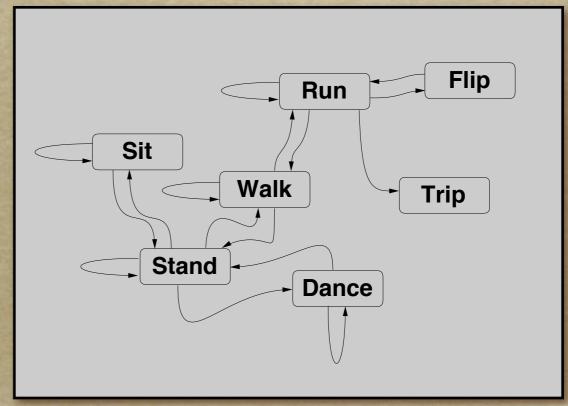
Transition Graphs

Transition Graphs



- Hand build motion graphs often used in games
 - Significant amount of work required
 - Limited transitions by design
- o Motion graphs can alsonbenbellits

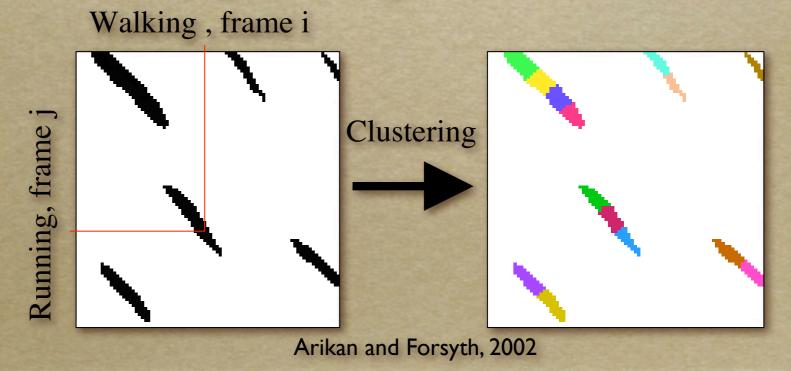
automatically



Similarity metric

- Measurement of how similar two frames of motion are
 - Based on joint angles or point positions
 - Must include some measure of velocity
 - Ideally independent of capture setup and skeleton
- Capture a "large" database of motions

- Compute similarity metric between all pairs of frames
 - Maybe expensive
 - Preprocessing step
 - There may be too many good edges

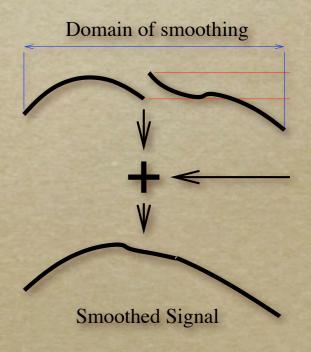


Random walks

- Start in some part of the graph and randomly make transitions
- Avoid dead ends
- Useful for "idling" behaviors

Transitions

Use blending algorithm we discussed



Match imposed requirements

- Start at a particular location
- End at a particular location
- Pass through particular pose
- Can be solved using dynamic programing
- Efficiency issues may require approximate solution
- Notion of "goodness" of a solution

Suggested Reading

- Fourier principles for emotion-based human figure animation, Unuma, Anjyo, and Takeuchi, SIGGRAPH 95
- Motion signal processing, Bruderlin and Williams, SIGGRAPH 95
- Motion warping, Witkin and Popovic, SIGGRAPH 95
- Efficient generation of motion transitions using spacetime constrains, Rose et al.,
 SIGGRAPH 96
- Retargeting motion to new characters, Gleicher, SIGGRAPH 98
- Verbs and adverbs: Multidimensional motion interpolation, Rose, Cohen, and Bodenheimer, IEEE: Computer Graphics and Applications, v. 18, no. 5, 1998

Suggested Reading

- Retargeting motion to new characters, Gleicher, SIGGRAPH 98
- Footskate Cleanup for Motion Capture Editing, Kovar, Schreiner, and Gleicher, SCA 2002.
- Interactive Motion Generation from Examples, Arikan and Forsyth, SIGGRAPH 2002.
- Motion Synthesis from Annotations, Arikan, Forsyth, and O'Brien, SIGGRAPH 2003.
- Pushing People Around, Arikan, Forsyth, and O'Brien, unpublished.
- Automatic Joint Parameter Estimation from Magnetic Motion Capture Data,
 O'Brien, Bodenheimer, Brostow, and Hodgins, GI 2000.
- Skeletal Parameter Estimation from Optical Motion Capture Data, Kirk, O'Brien, and Forsyth, CVPR 2005.
- Perception of Human Motion with Different Geometric Models, Hodgins, O'Brien, and Tumblin, IEEE:TVCG 1998.